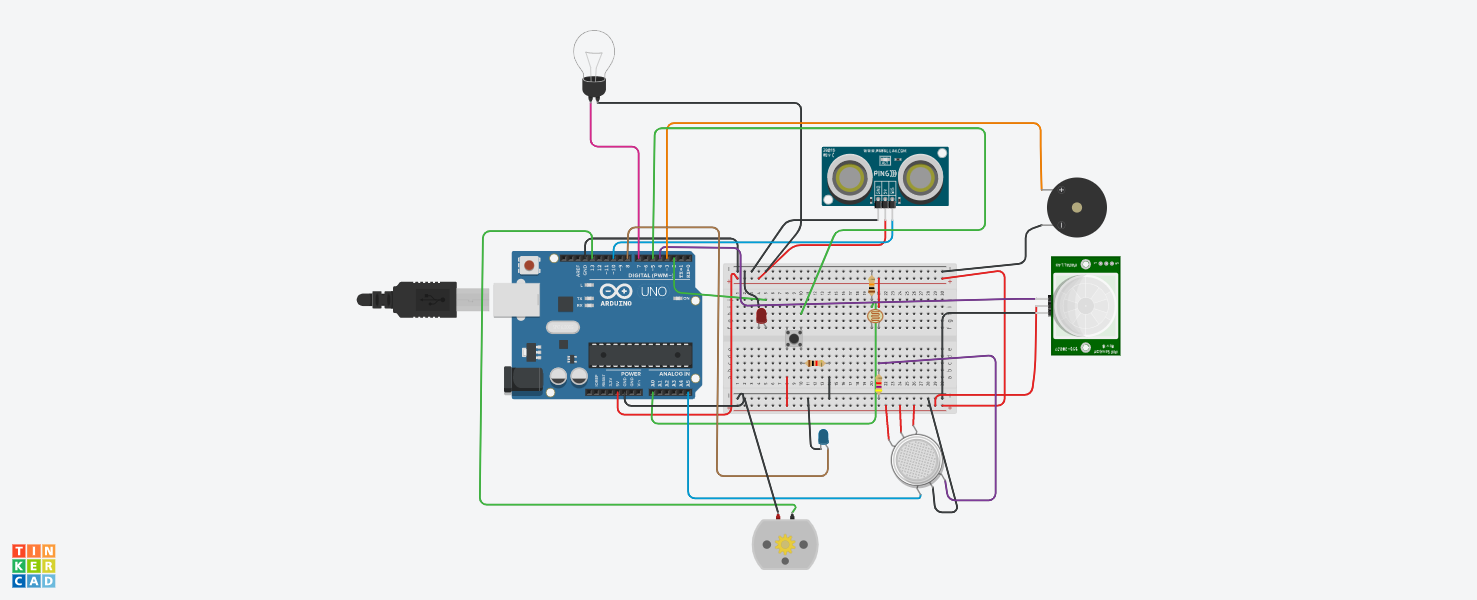
CIRCUIT DIAGRAM :



CODE:

const int pingPin = 10;

const int ledUS = 2;

const int light = 7;

const int pir = 4;

#define photoSensor A0

#define buzzer 3

int const PINO\_SGAS = A5;

int const ledGas = 8;

int const button = 5;

int const motor = 13;

void setup()

{

pinMode(ledUS, OUTPUT);

pinMode(light, OUTPUT);

pinMode(buzzer, OUTPUT);

pinMode(ledGas, OUTPUT);

pinMode(motor, OUTPUT);

pinMode(pir, INPUT);

pinMode(button, INPUT);

pinMode(photoSensor, INPUT);

Serial.begin(9600);

}

void loop()

{

long duration, cm;

int valLight = analogRead(photoSensor);

int valPIR= digitalRead(pir);

int valGAS = analogRead(PINO\_SGAS);

valGAS = map(valGAS, 300, 750, 0, 100);

int valBt = digitalRead(button);

pinMode(pingPin, OUTPUT);

digitalWrite(pingPin, LOW);

delayMicroseconds(2);

digitalWrite(pingPin, HIGH);

delayMicroseconds(5);

digitalWrite(pingPin, LOW);

pinMode(pingPin, INPUT);

duration = pulseIn(pingPin, HIGH);

cm = microsecondsToCentimeters(duration);

if(cm < 336){

digitalWrite(ledUS, HIGH);

}else{

digitalWrite(ledUS, LOW);

}

if(valLight < 890){

digitalWrite(light, HIGH);

}else{

digitalWrite(light, LOW);

}

if(valPIR == 1){

digitalWrite(buzzer, HIGH);

}else{

digitalWrite(buzzer, LOW);

}

if(valBt == 1){

digitalWrite(motor, HIGH);

}else{

digitalWrite(motor, LOW);

}

if(valGAS > 20){

digitalWrite(ledGas, HIGH);

}else{

digitalWrite(ledGas, LOW);

}

Serial.print(valPIR);

Serial.println();

}

long microsecondsToCentimeters(long microseconds) {

return microseconds / 29 / 2;